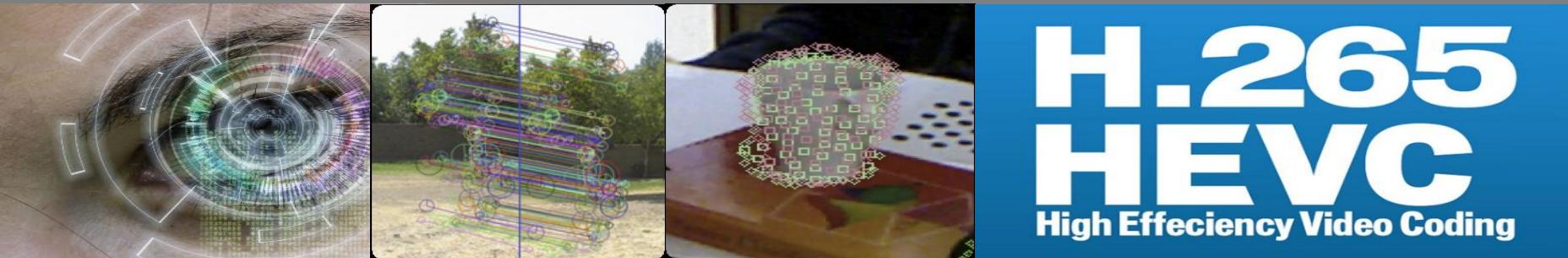


# Deep Learning Basics

## (#xx: Keras-based Convolutional Neural Network Practice-Part3)



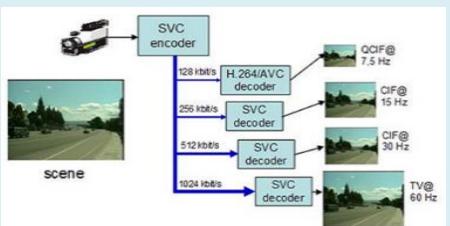
2023 Autumn

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## Gaol of this lecture

- ❖ Understand structure and how to set Google Tensorflow-based Objection Detection API
  - How to set the environment for Google Tensorflow API?
  - How to run object detection of Google Tensorflow API?
  - Run the object detection API using Webcam (live)?



## Contents

---

- What is Google Object Detection API?

# Google Objection Detection API (1)

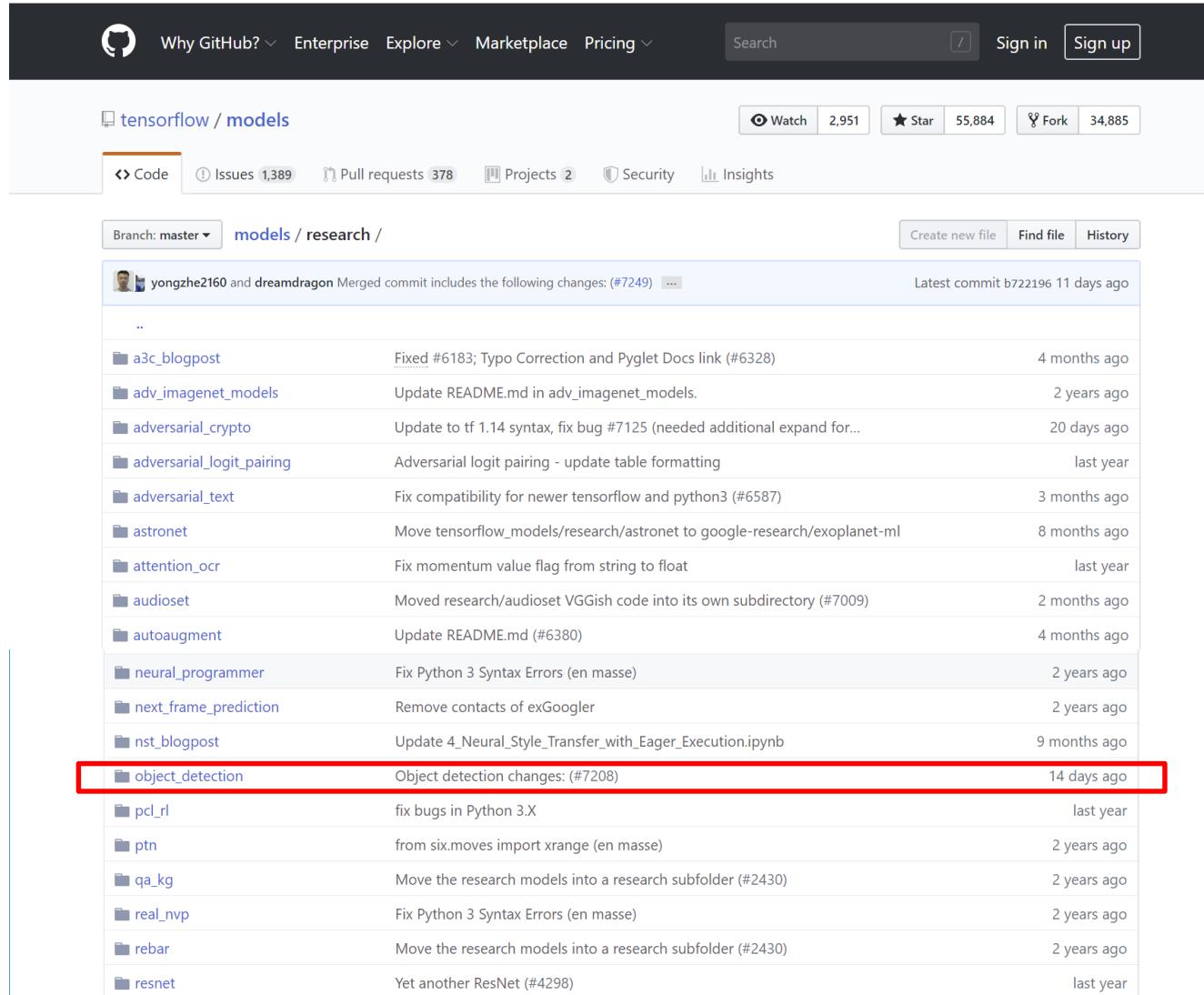
- ❖ Creating accurate machine learning models capable of localizing and identifying multiple objects in a single image remains a core challenge in computer vision.
  - Based on Tensorflow framework (open source framework)
  - <https://github.com/tensorflow/models/tree/master/research>



# Google Objection Detection API (1)

## ❖ Getting the source

- <https://github.com/tensorflow/models/tree/master/research>

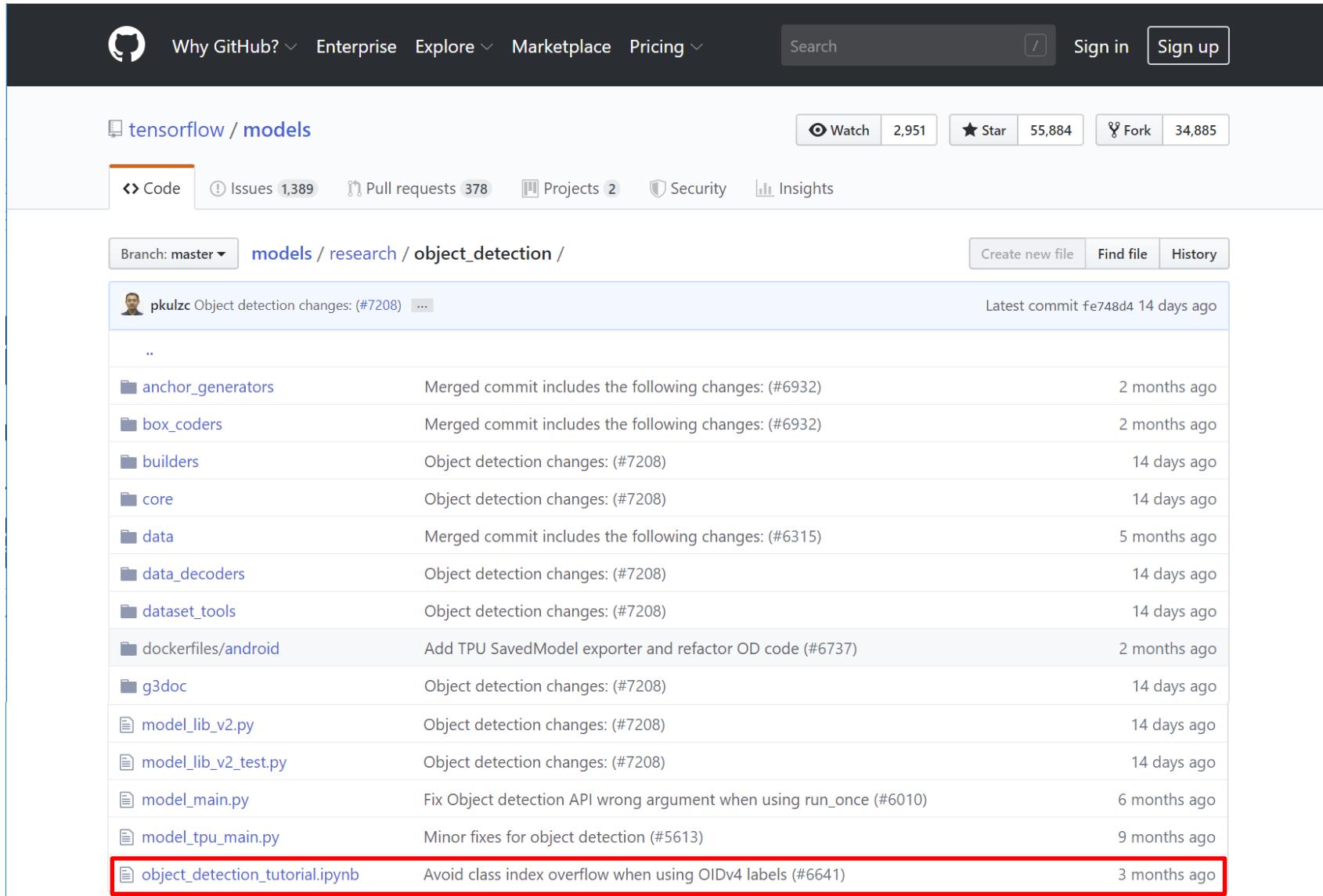


The screenshot shows the GitHub repository page for `tensorflow / models`. The repository has 1,389 issues, 378 pull requests, 2 projects, and 55,884 stars. The `Code` tab is selected. A dropdown menu shows the branch is set to `master`. The search bar contains `models / research /`. The commit list includes:

Author	Commit Message	Time Ago
yongzhe2160 and dreamdragon	Merged commit includes the following changes: (#7249) ...	Latest commit b722196 11 days ago
a3c_blogpost	Fixed #6183; Typo Correction and Pyglet Docs link (#6328)	4 months ago
adv_imagenet_models	Update README.md in adv_imagenet_models.	2 years ago
adversarial_crypto	Update to tf 1.14 syntax, fix bug #7125 (needed additional expand for...)	20 days ago
adversarial_logit_pairing	Adversarial logit pairing - update table formatting	last year
adversarial_text	Fix compatibility for newer tensorflow and python3 (#6587)	3 months ago
astronet	Move tensorflow_models/research/astronet to google-research/exoplanet-ml	8 months ago
attention_ocr	Fix momentum value flag from string to float	last year
audioset	Moved research/audioset VGGish code into its own subdirectory (#7009)	2 months ago
autoaugment	Update README.md (#6380)	4 months ago
neural_programmer	Fix Python 3 Syntax Errors (en masse)	2 years ago
next_frame_prediction	Remove contacts of exGoogler	2 years ago
nst_blogpost	Update 4_Neural_Style_Transfer_with_Eager_Execution.ipynb	9 months ago
object_detection	Object detection changes: (#7208)	14 days ago
pcl_rl	fix bugs in Python 3.X	last year
ptn	from six.moves import xrange (en masse)	2 years ago
qa_kg	Move the research models into a research subfolder (#2430)	2 years ago
real_nvp	Fix Python 3 Syntax Errors (en masse)	2 years ago
rebar	Move the research models into a research subfolder (#2430)	2 years ago
resnet	Yet another ResNet (#4298)	last year

# Google Objection Detection API (2)

- [https://github.com/tensorflow/models/tree/master/research/object\\_detection/](https://github.com/tensorflow/models/tree/master/research/object_detection/)



The screenshot shows the GitHub repository `tensorflow / models`. The `object_detection` branch is selected. The commit history for this branch is displayed, showing various commits from different authors (e.g., pkulzc, g3doc) across different files like `anchor_generators`, `box_coders`, `core`, etc. The commit at the bottom, which added a tutorial notebook, is highlighted with a red border.

Commit	Message	Date
<code>object_detection_tutorial.ipynb</code>	Avoid class index overflow when using OIDv4 labels (#6641)	3 months ago
<code>model_tpu_main.py</code>	Minor fixes for object detection (#5613)	9 months ago
<code>model_main.py</code>	Fix Object detection API wrong argument when using run_once (#6010)	6 months ago
<code>model_lib_v2_test.py</code>	Object detection changes: (#7208)	14 days ago
<code>model_lib_v2.py</code>	Object detection changes: (#7208)	14 days ago
<code>g3doc</code>	Object detection changes: (#7208)	14 days ago
<code>dockerfiles/android</code>	Add TPU SavedModel exporter and refactor OD code (#6737)	2 months ago
<code>dataset_tools</code>	Object detection changes: (#7208)	14 days ago
<code>data_decoders</code>	Object detection changes: (#7208)	14 days ago
<code>data</code>	Merged commit includes the following changes: (#6315)	5 months ago
<code>core</code>	Object detection changes: (#7208)	14 days ago
<code>builders</code>	Object detection changes: (#7208)	14 days ago
<code>box_coders</code>	Merged commit includes the following changes: (#6932)	2 months ago
<code>anchor_generators</code>	Merged commit includes the following changes: (#6932)	2 months ago
<code>pkulzc</code> Object detection changes: (#7208) ...	Latest commit fe748d4 14 days ago	

# Google Objection Detection API (3): Configurations

## ❖ My folder (after copying)

The image displays two windows side-by-side, both showing file structures. The left window is a standard Windows File Explorer view of a folder named 'research'. The right window is a more detailed list view of the same folder structure, specifically focusing on the 'object\_detection' folder.

**Left Window (File Explorer View):**

- Path: 내 PC > 로컬 디스크 (C:) > 사용자 > vicl > practices > TensorflowAPI > research
- Content: A list of subfolders and files, including 'adv\_imagenet\_models', 'adversarial\_crypto', 'adversarial\_text', 'astronet', 'attention\_ocr', 'audioset', 'autoencoder', 'brain\_coder', 'cognitive\_mapping\_and\_planning', 'compression', 'deplab', 'delf', 'differential\_privacy', 'domain\_adaptation', 'fivo', 'gan', 'im2txt', 'inception', 'learned\_optimizer', 'learning\_to\_remember\_rare\_events', 'learning\_unsupervised\_learning', 'lexnet\_nc', 'lfads', 'lm\_1b', 'maskgan', 'minigo', 'namigner', 'neural\_gpu', 'neural\_programmer', 'next\_frame\_prediction', and 'object\_detection' (which is selected).

**Right Window (Detailed List View):**

- Path: vicl > practices > TensorflowAPI > research > object\_detection
- Content: A detailed list of files and folders:

이름	수정한 날짜	유형	크기
models	2019-07-29 오후...	파일 폴더	
protos	2019-07-29 오후...	파일 폴더	
samples	2019-07-29 오후...	파일 폴더	
ssd_mobilenet_v1_coco_2017_11_17	2019-07-29 오후...	파일 폴더	
test_ckpt	2019-07-29 오후...	파일 폴더	
test_data	2019-07-29 오후...	파일 폴더	
test_images	2019-07-29 오후...	파일 폴더	
utils	2019-07-29 오후...	파일 폴더	
_init_	2018-04-25 오후...	Python File	0KB
CONTRIBUTING.md	2018-04-25 오후...	MD 파일	1KB
eval	2018-04-25 오후...	Python File	6KB
eval_util	2018-04-25 오후...	Python File	30KB
eval_util_test	2018-04-25 오후...	Python File	5KB
evaluator	2018-04-25 오후...	Python File	12KB
export_inference_graph	2018-04-25 오후...	Python File	7KB
exporter	2018-04-25 오후...	Python File	18KB
exporter_test	2018-04-25 오후...	Python File	41KB
inputs	2018-04-25 오후...	Python File	19KB
inputs_test	2018-04-25 오후...	Python File	24KB
Manual-20181011	2018-11-01 오후...	텍스트 문서	1KB
model_hparams	2018-04-25 오후...	Python File	2KB
model_lib	2018-04-25 오후...	Python File	28KB
model_lib_test	2018-04-25 오후...	Python File	17KB
model_main	2018-04-25 오후...	Python File	3KB
model_tpu_main	2018-04-25 오후...	Python File	5KB
object_detection_Streaming	2018-10-18 오후...	Python File	9KB
object_detection_Streaming_room_102	2018-11-02 오후...	Python File	9KB
object_detection_tutorial.ipynb	2018-04-26 오후...	IPYNB 파일	13KB
object_detection_tutorial	2018-04-26 오후...	Python File	8KB
object_detection_tutorial_video	2018-05-10 오후...	Python File	8KB
object_detection_tutorial_video_rev	2018-10-11 오후...	Python File	8KB
object_detections_GPU-then-CPU.ipynb	2018-05-10 오후...	IPYNB 파일	8KB
object_detections_GPU-then-CPU	2018-10-11 오후...	Python File	6KB
object_detections_GPU-then-CPU_Final	2018-10-11 오후...	Python File	6KB
object_detections_GPU-then-CPU_Final2	2019-07-29 오후...	Python File	7KB
object_detections_GPU-then-CPU_rev	2018-05-10 오후...	Python File	6KB

# Google Objection Detection API (4): Configurations

- ❖ Install cv2 (open CV module) package

```
(BGKim) C:\Users\vicl>pip install opencv-python
```

```
(BGKim) C:\Users\vicl>pip install opencv-python
Collecting opencv-python
  Downloading https://files.pythonhosted.org/packages/a3/50/04d0669afe884f137c2f490642756e8c4a658254300a9eaf253d1e643085/opencv_python-4.
1.0.25-cp37-cp37m-win_amd64.whl (37.3MB)
    |████████| 37.4MB 3.3MB/s
Requirement already satisfied: numpy>=1.14.5 in c:\programdata\anaconda3\envs\bgkim\lib\site-packages (from opencv-python) (1.16.4)
Installing collected packages: opencv-python
Successfully installed opencv-python-4.1.0.25

(BGKim) C:\Users\vicl>
(BGKim) C:\Users\vicl>
```

## Google (object detection) API Installation:

[https://github.com/tensorflow/models/blob/master/research/object\\_detection/g3doc/installation.md](https://github.com/tensorflow/models/blob/master/research/object_detection/g3doc/installation.md)

# Google Objection Detection API (5): Run API with Cam..!!!

- ❖ Go to the “object\_dection” folder and run “object\_detection\_tutorial.py”

```
(BGKim) C:\Users\vic\practices\TensorflowAPI\research\object_detection>python object_detections_GPU-then-CPU_Final2.py
width = 640, height = 480 720
WARNING: Logging before flag parsing goes to stderr.
[W0729 18:12:05.312280 26652 deprecation_wrapper.py:119] From object_detections_GPU-then-CPU_Final2.py:55: The name tf.Session is deprecated. Please use tf.compat.v1.Session instead.

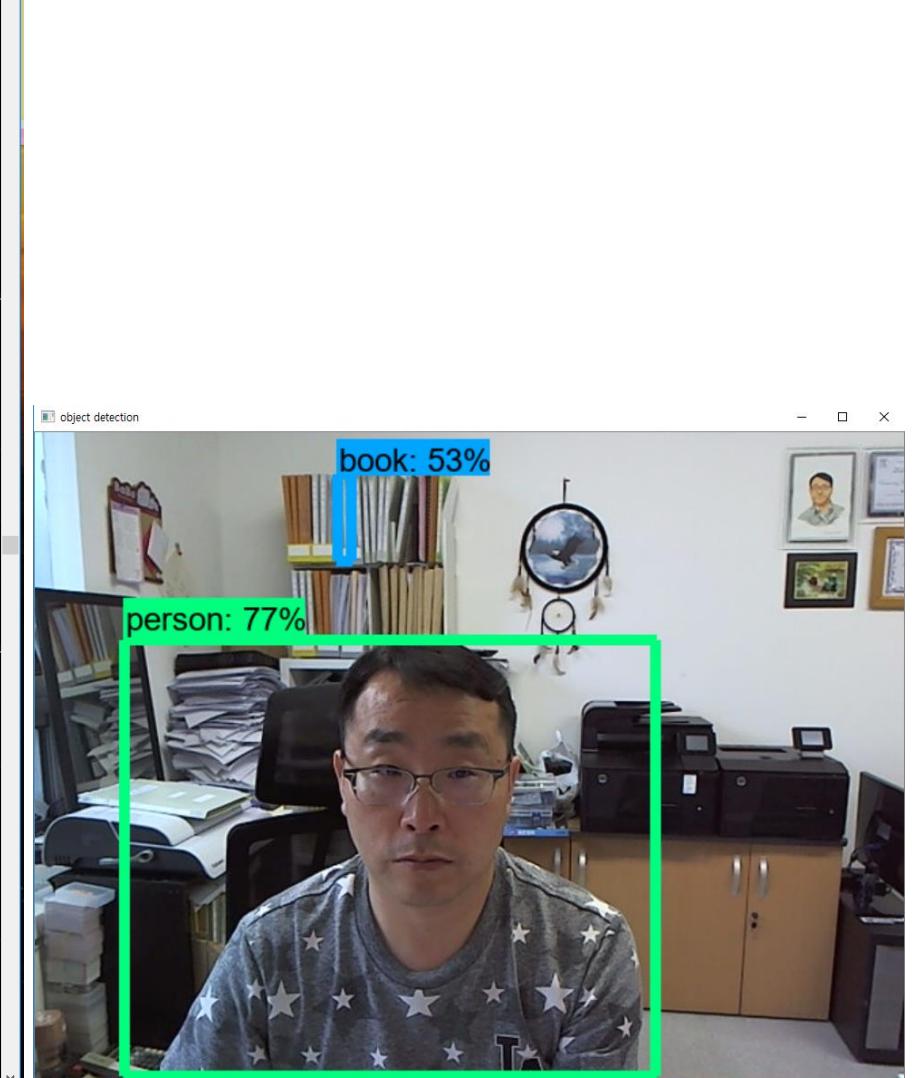
2019-07-29 18:12:05.314197: I tensorflow/stream_executor/platform/default/dso_loader.cc:42] Successfully opened dynamic library nvcuda.dll
2019-07-29 18:12:05.422849: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1640] Found device 0 with properties:
name: GeForce GTX 1070 Ti major: 6 minor: 1 memoryClockRate(GHz): 1.683
pciBusID: 0000:01:00.0
2019-07-29 18:12:05.430335: I tensorflow/stream_executor/platform/default/dlopen_checker_stub.cc:25] GPU libraries are statically linked, skip dlopen check.
2019-07-29 18:12:05.438956: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1763] Adding visible gpu devices: 0
2019-07-29 18:12:05.442641: I tensorflow/core/platform/cpu_feature_guard.cc:142] Your CPU supports instructions that this TensorFlow binary was not compiled to use: AVX2
2019-07-29 18:12:05.450515: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1640] Found device 0 with properties:
name: GeForce GTX 1070 Ti major: 6 minor: 1 memoryClockRate(GHz): 1.683
pciBusID: 0000:01:00.0
2019-07-29 18:12:05.456573: I tensorflow/stream_executor/platform/default/dlopen_checker_stub.cc:25] GPU libraries are statically linked, skip dlopen check.
2019-07-29 18:12:05.465620: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1763] Adding visible gpu devices: 0
2019-07-29 18:12:05.489247: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1181] Device interconnect StreamExecutor with strength 1 edge matrix:
2019-07-29 18:12:05.943823: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1187]      0
2019-07-29 18:12:05.946833: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1200] 0:  N
2019-07-29 18:12:05.954691: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1326] Created TensorFlow device (/job:localhost/replica:0/task:0/device:GPU:0 with 6357 MB memory) -> physical GPU (device: 0, name: GeForce GTX 1070 Ti, pci bus id: 0000:01:00.0, compute capability: 6.1)
[W0729 18:12:05.964537 26652 deprecation_wrapper.py:119] From object_detections_GPU-then-CPU_Final2.py:56: The name tf.placeholder is deprecated. Please use tf.compat.v1.placeholder instead.

[W0729 18:12:05.966533 26652 deprecation_wrapper.py:119] From object_detections_GPU-then-CPU_Final2.py:67: The name tf.GraphDef is deprecated. Please use tf.compat.v1.GraphDef instead.

[W0729 18:12:05.966533 26652 deprecation_wrapper.py:119] From object_detections_GPU-then-CPU_Final2.py:68: The name tf.gfile.GFile is deprecated. Please use tf.io.gfile.GFile instead.

[W0729 18:12:07.006775 26652 deprecation_wrapper.py:119] From object_detections_GPU-then-CPU_Final2.py:153: The name tf.ConfigProto is deprecated. Please use tf.compat.v1.ConfigProto instead.

2019-07-29 18:12:07.010673: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1640] Found device 0 with properties:
name: GeForce GTX 1070 Ti major: 6 minor: 1 memoryClockRate(GHz): 1.683
pciBusID: 0000:01:00.0
2019-07-29 18:12:07.017149: I tensorflow/stream_executor/platform/default/dlopen_checker_stub.cc:25] GPU libraries are statically linked, skip dlopen check.
2019-07-29 18:12:07.026666: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1763] Adding visible gpu devices: 0
2019-07-29 18:12:07.031596: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1181] Device interconnect StreamExecutor with strength 1 edge matrix:
2019-07-29 18:12:07.036820: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1187]      0
2019-07-29 18:12:07.041286: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1200] 0:  N
2019-07-29 18:12:07.048895: I tensorflow/core/common_runtime/gpu/gpu_device.cc:1326] Created TensorFlow device (/job:localhost/replica:0/task:0/device:GPU:0 with 6357 MB memory) -> physical GPU (device: 0, name: GeForce GTX 1070 Ti, pci bus id: 0000:01:00.0, compute capability: 6.1)
```



# Google Objection Detection API (6): Algorithms

- Source Insight

```
import numpy as np
import os
import sys

# This is needed since the notebook is stored in
# the object_detection folder.
sys.path.append(".")

import tensorflow as tf
import time
import copy

from tensorflow.core.framework import graph_pb2
from utils import label_map_util
from utils import visualization_utils as vis_util
from matplotlib import pyplot as plt
from PIL import Image

import cv2
cap = cv2.VideoCapture(0)
(continue)
```

```
def _node_name(n):
    if n.startswith("^"):
        return n[1:]
    else:
        return n.split(":")[0]

input_graph = tf.Graph()
with tf.Session(graph=input_graph):
    score = tf.placeholder(tf.float32, shape=(None, 1917,
                                              90), name="Postprocessor/convert_scores")
    expand = tf.placeholder(tf.float32, shape=(None, 1917,
                                                1, 4), name="Postprocessor/ExpandDims_1")
    for node in input_graph.as_graph_def().node:
        if node.name == "Postprocessor/convert_scores":
            score_def = node
        if node.name == "Postprocessor/ExpandDims_1":
            expand_def = node

(continue)
```

# Google Objection Detection API (7): Algorithms

```
detection_graph = tf.Graph()
with detection_graph.as_default():
    od_graph_def = tf.GraphDef()
    with tf.gfile.GFile('./ssd_mobilenet_v1_coco_2017_11_17/frozen_inference_graph.pb', 'rb') as fid:
        serialized_graph = fid.read()
        od_graph_def.ParseFromString(serialized_graph)
        dest_nodes = ['Postprocessor/convert_scores', 'Postprocessor/ExpandDims_1']

    edges = {}
    name_to_node_map = {}
    node_seq = {}
    seq = 0
    for node in od_graph_def.node:
        n = _node_name(node.name)
        name_to_node_map[n] = node
        edges[n] = [_node_name(x) for x in node.input]
        node_seq[n] = seq
        seq += 1

    for d in dest_nodes:
        assert d in name_to_node_map, "%s is not in graph" % d

    nodes_to_keep = set()
    next_to_visit = dest_nodes[:]
    (continue)
```

# Google Objection Detection API (8): Algorithms

```
while next_to_visit:  
    n = next_to_visit[0]  
    del next_to_visit[0]  
    if n in nodes_to_keep:  
        continue  
    nodes_to_keep.add(n)  
    next_to_visit += edges[n]  
  
nodes_to_keep_list = sorted(list(nodes_to_keep), key=lambda n: node_seq[n])  
  
nodes_to_remove = set()  
for n in node_seq:  
    if n in nodes_to_keep_list: continue  
    nodes_to_remove.add(n)  
nodes_to_remove_list = sorted(list(nodes_to_remove), key=lambda n: node_seq[n])  
  
keep = graph_pb2.GraphDef()  
for n in nodes_to_keep_list:  
    keep.node.extend([copy.deepcopy(name_to_node_map[n])])  
  
remove = graph_pb2.GraphDef()  
remove.node.extend([score_def])  
remove.node.extend([expand_def])  
for n in nodes_to_remove_list:  
    remove.node.extend([copy.deepcopy(name_to_node_map[n])]) # continue
```

# Google Objection Detection API (9): Algorithms

```
with tf.device('/gpu:0'):
    tf.import_graph_def(keep, name=' ')
with tf.device('/cpu:0'):
    tf.import_graph_def(remove, name=' ')

PATH_TO_LABELS = os.path.join('C:/tensorflow/models/research/object_detection/data',
    'mscoco_label_map.pbtxt')

NUM_CLASSES = 90
label_map = label_map_util.load_labelmap(os.path.join(PATH_TO_LABELS))
#label_map = label_map_util.load_labelmap('data/mscoco_label_map.pbtxt')
categories = label_map_util.convert_label_map_to_categories(label_map, max_num_classes=NUM_CLASSES,
use_display_name=True)
category_index = label_map_util.create_category_index(categories)

def load_image_into_numpy_array(image):
    (im_width, im_height) = image.size
    return np.array(image.getdata()).reshape((im_height, im_width, 3)).astype(np.uint8)
```

(continue)

# Google Objection Detection API (10): Algorithms

```
# For the sake of simplicity we will use only 2 images:  
# image1.jpg  
# image2.jpg  
# If you want to test the code with your images, just add path to the images to the TEST_IMAGE_PATHS.  
PATH_TO_TEST_IMAGES_DIR = 'C:/tensorflow/models/research/object_detection/test_images'  
TEST_IMAGE_PATHS = [ os.path.join(PATH_TO_TEST_IMAGES_DIR, 'image{}.jpg'.format(i)) for i in range(1, 3) ]  
  
# Size, in inches, of the output images.  
IMAGE_SIZE = (12, 8)  
  
# In[6]:  
  
with detection_graph.as_default():  
    with tf.Session(graph=detection_graph, config=tf.ConfigProto(allow_soft_placement=True)) as sess:  
        image_tensor = detection_graph.get_tensor_by_name('image_tensor:0')  
        score_out = detection_graph.get_tensor_by_name('Postprocessor/convert_scores:0')  
        expand_out = detection_graph.get_tensor_by_name('Postprocessor/ExpandDims_1:0')  
        score_in = detection_graph.get_tensor_by_name('Postprocessor/convert_scores_1:0')  
        expand_in = detection_graph.get_tensor_by_name('Postprocessor/ExpandDims_1_1:0')  
        detection_boxes = detection_graph.get_tensor_by_name('detection_boxes:0')  
        detection_scores = detection_graph.get_tensor_by_name('detection_scores:0')  
        detection_classes = detection_graph.get_tensor_by_name('detection_classes:0')  
        num_detections = detection_graph.get_tensor_by_name('num_detections:0')  
        i = 0
```

# Google Objection Detection API (10): Algorithms

```
while True:          # Webcam case
#for _ in range(10): # Image case
#image_path = TEST_IMAGE_PATHS[1]
#i += 1
#image = Image.open(image_path)
#image_np = load_image_into_numpy_array(image)
ret, image_np = cap.read()
image_np_expanded = np.expand_dims(image_np, axis=0)

start_time = time.time()
(score, expand) = sess.run([score_out, expand_out], feed_dict={image_tensor: image_np_expanded})
(boxes, scores, classes, num) = sess.run(
    [detection_boxes, detection_scores, detection_classes, num_detections],
    feed_dict={score_in:score, expand_in: expand})
#print 'Iteration %d: %.3f sec'%(i, time.time()-start_time)

vis_util.visualize_boxes_and_labels_on_image_array(image_np, np.squeeze(boxes),
np.squeeze(classes).astype(np.int32),
np.squeeze(scores),
category_index,
use_normalized_coordinates=True,
line_thickness=8)
(continue)
```

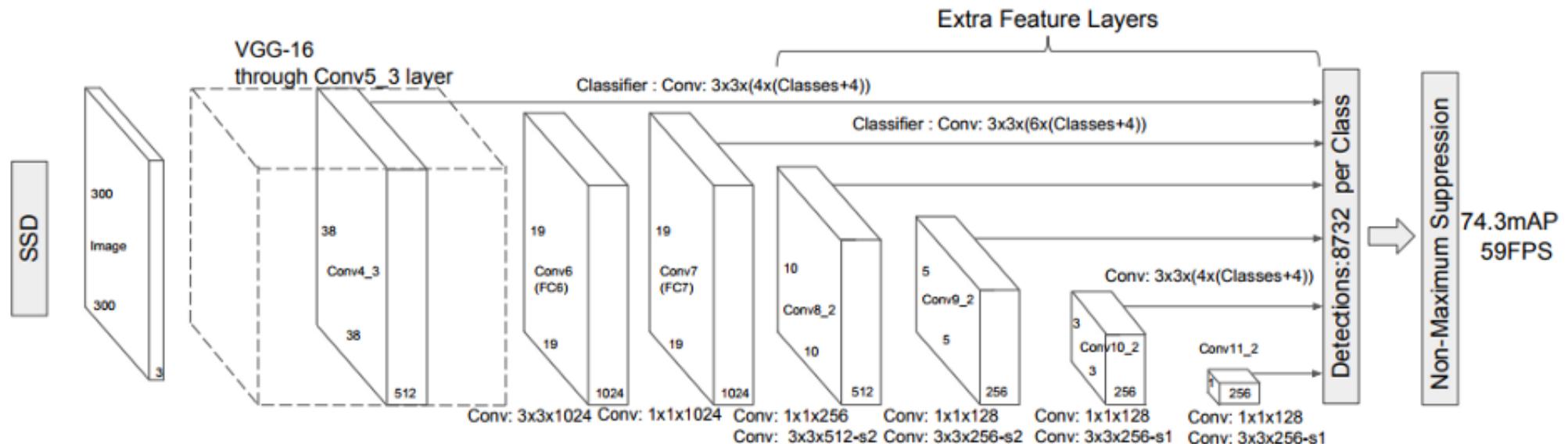
# Google Objection Detection API (11): Algorithms

```
(continue)
#cv2.imshow('object detection', cv2.resize(image_np, (800,600)))
cv2.imshow('object detection', cv2.resize(image_np, (width,height)))
#cv2.imshow('object detection', cv2.resize(image_np, (1080, 720)))
if cv2.waitKey(25) & 0xff == ord('q'):
    cv2.destroyAllWindows()
    break

# plt.figure(figsize=IMAGE_SIZE)
# plt.imshow(image_np)
```

# Google Objection Detection API (12): Algorithms

- ❖ Network Model: SSD (Single-Shot Multibox Detector ([SSD](#))) (VGG-16)



# Google Objection Detection API (13): Main Procedure of API

## ❖ Tensorflow Graph():

```
input_graph = tf.Graph()      ← A TensorFlow computation, represented as a dataflow graph.  
with tf.Session(graph=input_graph):
```

## ❖ GraphDef():

```
od_graph_def = tf.GraphDef()  ← Create TensorFlow protocol buffer .
```

## ❖ Tf.placeholder():

- Inserts a placeholder for a tensor that will be always fed.

```
score = tf.placeholder(tf.float32, shape=(None, 1917, 90),  
name="Postprocessor/convert_scores")
```

```
x = tf.compat.v1.placeholder(tf.float32, shape=(1024, 1024))  
y = tf.matmul(x, x)  
  
with tf.compat.v1.Session() as sess:  
    print(sess.run(y)) # ERROR: will fail because x was not fed.  
  
    rand_array = np.random.rand(1024, 1024)  
    print(sess.run(y, feed_dict={x: rand_array})) # Will succeed.
```

# Google Objection Detection API (14): Main Procedure of API

## ❖ Tensorflow Session():

```
with tf.Session(graph=input_graph): ← A class for running TensorFlow operations.
```

## ❖ tf.gfile.GFile():

- Load or save file data in Python.

```
with tf.gfile.GFile('./ssd_mobilenet_v1_coco_2017_11_17/frozen_inference_graph.pb', 'rb') as fid:
```

Python example

```
with gfile.GFile(filepath, "w") as file:  
    file.write(result_str)
```

## ❖ with tf.device('/gpu:0'):

- Supporting devices (CPU or GPU) manually.

```
# Creates a graph.  
with tf.device('/cpu:0'):  
    a = tf.constant([1.0, 2.0, 3.0, 4.0, 5.0, 6.0], shape=[2, 3], name='a')  
    b = tf.constant([1.0, 2.0, 3.0, 4.0, 5.0, 6.0], shape=[3, 2], name='b')  
    c = tf.matmul(a, b)  
# Creates a session with log_device_placement set to True.  
sess = tf.Session(config=tf.ConfigProto(log_device_placement=True))  
# Runs the op.  
print(sess.run(c))
```



Device mapping:  
/job:localhost/replica:0/task:0/device:GPU:0 -> device: 0, name: Tesla K40c, pci bus  
id: 0000:05:00.0  
b: /job:localhost/replica:0/task:0/cpu:0  
a: /job:localhost/replica:0/task:0/cpu:0  
MatMul: /job:localhost/replica:0/task:0/device:GPU:0  
[[ 22. 28.]  
 [ 49. 64.]]

# Google Objection Detection API (15): Main Procedure of API

- ❖ PATH\_TO\_LABELS =  
os.path.join('C:/tensorflow/models/research/object\_detection/data',  
'mscoco\_label\_map.pbtxt')
  - Set the path and file location for Label data.
- ❖ sess.run(args)
  - Execute the tensorflow with the predefined parameters and environment.

```
import tensorflow as tf

x = tf.placeholder(tf.float32, shape=[3])
y = tf.square(x)

with tf.Session() as sess:
    # 텐서 y를 계산하려면 필요한 플레이스홀더 이름 x와
    # 플레이스홀더에서 사용할 값을 딕셔너리 형태로 입력해줍니다.
    print(sess.run(y, {x: [1.0, 2.0, 3.0]}))
    print(sess.run(y, {x: [4.0, 5.0, 6.0]}))
```

# Google Objection Detection API (16): Models

## ❖ COCO-pre trained models

Model name	Speed (ms)	COCO mAP[^1]	Outputs
ssd_mobilenet_v1_coco	30	21	Boxes
ssd_mobilenet_v1_0.75_depth_coco ☆	26	18	Boxes
ssd_mobilenet_v1_quantized_coco ☆	29	18	Boxes
ssd_mobilenet_v1_0.75_depth_quantized_coco ☆	29	16	Boxes
ssd_mobilenet_v1_ppn_coco ☆	26	20	Boxes
ssd_mobilenet_v1_fpn_coco ☆	56	32	Boxes
ssd_resnet_50_fpn_coco ☆	76	35	Boxes
ssd_mobilenet_v2_coco	31	22	Boxes
ssd_mobilenet_v2_quantized_coco	29	22	Boxes
ssdlite_mobilenet_v2_coco	27	22	Boxes
ssd_inception_v2_coco	42	24	Boxes
faster_rcnn_inception_v2_coco	58	28	Boxes
faster_rcnn_resnet50_coco	89	30	Boxes
faster_rcnn_resnet50_lowproposals_coco	64		Boxes
rfcn_resnet101_coco	92	30	Boxes
faster_rcnn_resnet101_coco	106	32	Boxes
faster_rcnn_resnet101_lowproposals_coco	82		Boxes
faster_rcnn_inception_resnet_v2_atrous_coco	620	37	Boxes
faster_rcnn_inception_resnet_v2_atrous_lowproposals_coco	241		Boxes
faster_rcnn_nas	1833	43	Boxes
faster_rcnn_nas_lowproposals_coco	540		Boxes
mask_rcnn_inception_resnet_v2_atrous_coco	771	36	Masks
mask_rcnn_inception_v2_coco	79	25	Masks
mask_rcnn_resnet101_atrous_coco	470	33	Masks
mask_rcnn_resnet50_atrous_coco			

```
# What model to download.  
MODEL_NAME = 'mask_rcnn_inception_v2_coco_2018_01_28'  
MODEL_FILE = MODEL_NAME + '.tar.gz'  
DOWNLOAD_BASE =  
'http://download.tensorflow.org/models/object_detection/'  
  
# Path to frozen detection graph. This is the actual model that  
# is used for the object detection.  
PATH_TO_CKPT = MODEL_NAME + '/frozen_inference_graph.pb'
```

*Change Model that you want to use....!!!*

**Thank you for your attention!!!  
QnA**

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